

# Convexity

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# Why should I bother to learn this stuff?

- Convex vocabulary and results are needed throughout the course, especially to obtain optimality conditions and duality relations.
- Convex analysis tools like Fenchel transform appears in modern machine learning theory
- $\implies$  fundamental for M2 in continuous optimization
- $\implies$  usefull for M2 in operation research, machine learning (and some part of probability or mechanics)

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- 1 Convex sets [BV 2]
  - Fundamental definitions
  - Separation theorems
- 2 Convex functions [BV 3]
  - definitions
  - Convex function and optimization
  - Some results on convex functions
- 3 Convex analysis
  - Subdifferential
  - Fenchel transform
- 4 Wrap-up

# Affine sets



Let  $X$  be a normed vector space (usually  $X = \mathbb{R}^n$ ), and  $C \subset X$

- $C$  is **affine** if it contains any lines going through two distinct points of  $C$ , i.e.,

$$\forall x, y \in C, \quad \forall \theta \in \mathbb{R}, \quad \theta x + (1 - \theta)y \in C.$$

- The **affine hull** of  $C$  is the set of **affine combination** of elements of  $C$ ,

$$\text{aff}(C) := \left\{ \sum_{i=1}^K \theta_i x_i \mid \forall x_i \in C, \forall \theta_i \in \mathbb{R}, \sum_{i=1}^K \theta_i = 1, \forall i \in [K], \forall K \in \mathbb{N} \right\}$$

- $\text{aff}(C)$  is the smallest affine space containing  $C$ .
- The **affine dimension** of  $C$  is the dimension of  $\text{aff}(C)$  (i.e., the dimension of the vector space  $\text{aff}(C) - x_0$  for  $x_0 \in C$ ).
- The **relative interior** of  $C$  is defined as

$$\text{ri}(C) := \left\{ x \in C \mid \exists r > 0, \quad B(x, r) \cap \text{aff}(C) \subset C \right\}$$



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$$\text{ri}(C) := \left\{ x \in C \mid \exists r > 0, \quad B(x, r) \cap \text{aff}(C) \subset C \right\}$$



- $C$  is **convex** if for any two points  $x$  and  $y$  in  $C$  the segment  $[x, y] \subset C$ , *i.e.*,

$$\forall x, y \in C, \forall \theta \in [0, 1], \theta x + (1 - \theta)y \in C.$$

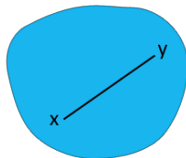
- The **convex hull** of  $C$  as the set of **convex combination** of elements of  $C$ , *i.e.*,

$$\text{conv}(C) := \left\{ \sum_{i=1}^K \theta_i x_i \mid \forall x_i \in C, \right.$$

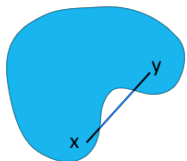
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- $\text{conv}(C)$  is the smallest convex set containing  $C$ .

Convex set



Non - convex set



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- $C$  is a **cone** if for all  $x \in C$  the **ray**  $\mathbb{R}_+x \subset C$ , i.e.,

$$\forall x \in C, \quad \forall \theta \in \mathbb{R}_+, \quad \theta x \in C.$$

- The (convex) **conic hull** of  $C$  is the set of all (convex) **conic combination** of elements of  $C$  i.e.,

$$\text{cone}(C) := \left\{ \sum_{i=1}^K \theta_i x_i \mid \forall x_i \in C, \forall \theta_i \in \mathbb{R}_+, \forall i \in [K], \forall K \in \mathbb{N} \right\}$$

- $\text{cone}(C)$  is the smallest **convex** cone containing  $C$ .
- A cone  $C$  is **pointed** if it does not contain any full line  $\mathbb{R}x$  for  $x \neq 0$ .
- For  $C$  convex,  $\text{cone}(C) = \bigcup_{t>0} tC$

# Examples

Let  $X = \mathbb{R}^n$ .

- Any affine space is convex.
- Any **hyperplane** of  $X$  can be defined as  $H := \{x \in X \mid a^\top x = b\}$  for well chosen  $a \in \mathbb{R}^n$  and  $b \in \mathbb{R}$  and is an affine space of dimension  $n - 1$ .
- $H$  divide  $X$  into two **half-spaces**  $\{x \in \mathbb{R}^n \mid a^\top x \leq b$  and  $\{x \in \mathbb{R}^n \mid a^\top x \geq b\}$  which are (closed) convex sets.
- For any norm  $\| \cdot \|$  the **ball**  $B_{\| \cdot \|}(x_0, r) := \{x \in X \mid \|x - x_0\| \leq r\}$  is a (closed) convex set.
  - ♣ Exercise: Prove it.
- The set  $C = \{(x, t) \in X \times \mathbb{R} \mid \|x\| \leq t\}$  is a cone.
- The set  $C = \{x \in X \mid Ax \leq b\}$  where  $A$  and  $b$  are given is a (closed) convex set called **polyhedron**.



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Assume that all sets denoted by  $C$  (indexed or not) are convex.

- $C_1 + C_2$  and  $C_1 \times C_2$  are convex sets.
- For any arbitrary index set  $\mathcal{I}$  the intersection  $\bigcap_{i \in \mathcal{I}} C_i$  is convex.
- Let  $f$  be an affine function. Then  $f(C)$  and  $f^{-1}(C)$  are convex.
- In particular,  $C + x_0$ , and  $tC$  are convex. The projection of  $C$  on any affine space is convex.
- The closure  $\text{cl}(C)$  and relative interior  $\text{ri}(C)$  are convex.

♣ Exercise: Prove these results.

# Perspective and linear-fractional function



Let  $P : \mathbb{R}^n \times \mathbb{R} \rightarrow \mathbb{R}^n$  be the **perspective function** defined as  $P(x, t) = x/t$ , with  $\text{dom}(P) = \mathbb{R}^n \times \mathbb{R}_+^*$ .

## Theorem

*If  $C \subset \text{dom}(P)$  is convex, then  $P(C)$  is convex.*

*If  $C \subset \mathbb{R}^n$  is convex, then  $P^{-1}(C)$  is convex.*

♠ Exercise: Prove this result.

## Perspective and linear-fractional function



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♠ Exercise: Prove this result.

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a **linear-fractional function** of the form  $f(x) := (Ax + b)/(c^\top x + d)$ , with  $\text{dom}(f) = \{x \mid c^\top x + d > 0\}$ .

### Theorem

*If  $C \subset \text{dom}(f)$  is convex, then  $f(C)$  and  $f^{-1}(C)$  are convex.*

♣ Exercise: prove this result.

# Cone ordering

Let  $K \subset \mathbb{R}^n$  be a closed, convex, pointed cone with non-empty interior. We define the **cone ordering** according to  $K$  by

$$x \preceq_K y \iff y - x \in K.$$

♣ Exercise: Prove that  $\preceq_K$  is a partial order (i.e., reflexive, antisymmetric, transitive) compatible with scalar product, addition and limits.

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# Separation



Let  $X$  be a Banach space, and  $X^*$  its **topological dual** (i.e. the set of all continuous linear forms on  $X$ ).

## Theorem (Simple separation)

Let  $A$  and  $B$  be convex non-empty, disjoint subsets of  $X$ . There exists a **separating hyperplane**  $(x^*, \alpha) \in X^* \times \mathbb{R}$  such that

$$\langle x^*, a \rangle \leq \alpha \leq \langle x^*, b \rangle \quad \forall a, b \in A \times B.$$

## Theorem (Strong separation)

Let  $A$  and  $B$  be convex non-empty, disjoint subsets of  $X$ . Assume that,  $A$  is closed, and  $B$  is compact (e.g. a point), then there exists a **strict separating hyperplane**  $(x^*, \alpha) \in X^* \times \mathbb{R}$  such that, there exists  $\varepsilon > 0$ ,

$$\langle x^*, a \rangle + \varepsilon \leq \alpha \leq \langle x^*, b \rangle - \varepsilon \quad \forall a, b \in A \times B.$$

Remark: these theorems require the Zorn Lemma which is equivalent to the axiom of choice.



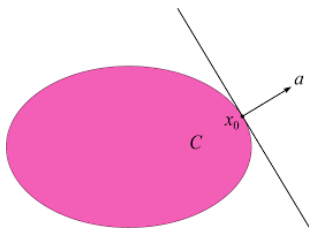
## Theorem

Let  $x_0 \notin \text{ri}(C)$  and  $C$  convex. Then there exists  $a \neq 0$  such that

$$a^T x \geq a^T x_0, \quad \forall x \in C$$

If  $x_0 \in C$ , say that

$H = \{x \mid a^T x = a^T x_0\}$  is a **supporting hyperplane** of  $C$  at  $x_0$ .



♣ Exercise: prove this theorem

Remark: there can be more than one supporting hyperplane at a given point.





- The **closed convex hull** of  $C \subset X$ , denoted  $\overline{\text{conv}}(C)$  is the smallest closed convex set containing  $C$ .
- $\overline{\text{conv}}(C)$  is the intersection of all the half-spaces containing  $C$ .
- A polyhedron is a finite intersection of half-spaces while a convex set is a possibly non-finite intersection of half-spaces.

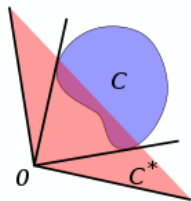
# Dual and normal cones

- Let  $C \subset \mathbb{R}^n$  be a set. We define its **dual cone** by

$$C^\oplus := \{x \mid x^\top c \geq 0, \quad \forall c \in C\}$$

- For any set  $C$ ,  $C^\oplus$  is a closed convex cone.
- The **normal cone** of  $C$  at  $x_0$  is

$$N_C(x_0) := \{\lambda \in E \mid \lambda^\top (x - x_0) \leq 0, \\ \forall x \in C\}$$



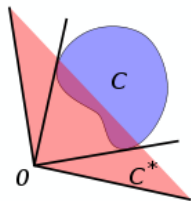
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# Examples

- The positive orthant  $K = \mathbb{R}_+^n$  is a **self dual** cone, that is  $K^\oplus = K$ .
- In the space of symmetric matrices  $S_n(\mathbb{R})$ , with the scalar product  $\langle A, B \rangle = \text{tr}(AB)$ , the set of positive semidefinite matrices  $K = S_n^+(\mathbb{R})$  is self dual.
- Let  $\|\cdot\|$  be a norm. The cone  $K = \{(x, t) \mid \|x\| \leq t\}$  has for dual  $K^\oplus = \{(\lambda, z) \mid \|\lambda\|_* \leq z\}$ , where  $\|\lambda\|_* := \sup_{x: \|x\| \leq 1} \lambda^\top x$ .

♠ Exercise: prove these results

# Some basic properties

Let  $K \subset \mathbb{R}^n$  be a cone.

- $K^\oplus$  is closed convex.
- $K_1 \subset K_2$  implies  $K_2^\oplus \subset K_1^\oplus$
- $K^{\oplus\oplus} = \overline{\text{conv}} K$

♣ Exercise: Prove these results

## Video resources

[https://www.youtube.com/watch?v=P3W\\_wFZ2kUo](https://www.youtube.com/watch?v=P3W_wFZ2kUo)

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# Functions with non finite values



- It is very useful in optimization to allow functions to take non-finite values, that is to take values in  $\bar{\mathbb{R}} := \mathbb{R} \cup \{-\infty, +\infty\}$ .
- If both  $-\infty$  and  $+\infty$  are allowed be very careful of each addition !
- Let  $f : X \rightarrow \bar{\mathbb{R}}$ . We define

- ▶ The **epigraph** of  $f$  as

$$\text{epi}(f) := \{(x, t) \in X \times \mathbb{R} \mid f(x) \leq t\}$$

- ▶ the **domain** of  $f$  as

$$\text{dom}(f) := \{x \in X \mid f(x) < +\infty\}.$$

- ▶ The **sublevel set** of level  $\alpha$

$$\text{lev}_\alpha(f) := \{x \in X \mid f(x) \leq \alpha\}.$$

- $f$  is said to be **lower semi continuous** (l.s.c.) if  $\text{epi}(f)$  is closed.
- $f$  is said to be **proper** if it never takes value  $-\infty$ , has a non-empty domain (at least one finite value).



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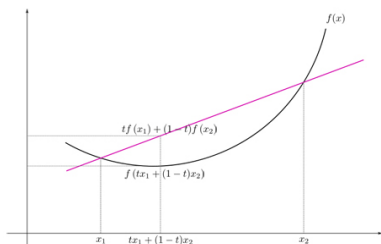
- A function  $f : X \rightarrow \bar{\mathbb{R}}$  is **convex** if its epigraph is convex.

- $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$  is convex iff

$$\forall t \in [0, 1], \forall x, y \in X,$$

$$f(tx + (1 - t)y) \leq tf(x) + (1 - t)f(y)$$

- $f$  is **concave** if  $-f$  is convex.





- If  $f, g$  convex,  $t > 0$ , then  $tf + g$  is convex.
- If  $f$  convex non-decreasing,  $g$  convex, then  $f \circ g$  convex.
- If  $f$  convex and  $a$  affine, then  $f \circ a$  is convex.
- If  $(f_i)_{i \in I}$  is a family of convex functions, then  $\sup_{i \in I} f_i$  is convex.
- The domain and the sublevel sets of a convex function are convex.
- A convex function is always above its tangents.

♣ Exercise: Prove these results.



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## Theorem (Jensen inequality)

Let  $f$  be a convex function and  $\mathbf{X}$  an integrable random variable. Then we have

$$f(\mathbb{E}[\mathbf{X}]) \leq \mathbb{E}[f(\mathbf{X})].$$



Consider a convex function  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ .

- $f$  is continuous (on  $\mathbb{R}^n$ ) if and only if  $\text{dom}(f) = \mathbb{R}^n$  (i.e., if it is finite everywhere)
- $f$  is continuous on the interior of its domain
- $f$  is lower-semicontinuous if and only if the domain is closed and the restriction of  $f$  to its domain is continuous

# Convex functions: strict and strong convexity



- $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$  is strictly convex iff

$$\forall t \in ]0, 1[, \quad \forall x, y \in X, \quad f(tx + (1-t)y) < tf(x) + (1-t)f(y)$$

- $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$  is  $\alpha$ -convex iff  $\forall t \in ]0, 1[, \quad \forall x, y \in X,$

$$f(tx + (1-t)y) \leq tf(x) + (1-t)f(y) - \frac{1}{2}\alpha t(1-t)\|x - y\|^2$$

- If  $f \in C^1(\mathbb{R}^n)$

- ▶  $\langle \nabla f(x) - \nabla f(y), x - y \rangle \geq 0$  iff  $f$  convex
- ▶ if strict inequality holds, then  $f$  strictly convex
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- If  $f \in C^2(\mathbb{R}^n),$

- ▶  $\nabla^2 f \succcurlyeq 0$  iff  $f$  convex
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- ▶ if  $\nabla^2 f \succcurlyeq \alpha I$  then  $f$  is  $\alpha$ -convex

# Important examples

- The **indicator function** of a set  $C \subset X$ ,

$$\mathbb{I}_C(x) := \begin{cases} 0 & \text{if } x \in C \\ +\infty & \text{otherwise} \end{cases}$$

is convex iff  $C$  is convex.

- $x \mapsto e^{ax}$  is convex for any  $a \in \mathbb{R}$
- $x \mapsto \|x\|^q$  is convex for  $q \geq 1$  and any norm
- $x \mapsto \ln(x)$  is concave
- $x \mapsto x \ln(x)$  is convex
- $x \mapsto \ln(\sum_{i=1}^n e^{x_i})$  is convex

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$$\text{Min}_{x \in C} f(x)$$

Where  $C$  is closed convex and  $f$  convex finite valued, is a **convex optimization problem**.

- If  $C$  is compact and  $f$  proper lsc, then there exists an optimal solution.
- If  $f$  is proper lsc and coercive, then there exists an optimal solution.
- The set of optimal solutions is convex.
- If  $f$  is strictly convex the minimum (if it exists) is unique.
- If  $f$  is  $\alpha$ -convex the minimum exists and is unique.

♣ Exercise: Prove these results.



Note that minimizing  $f$  over  $C$  or minimizing  $f + \mathbb{I}_C$  over  $X$  is the same thing.

We consider the (unconstrained) optimization problem

$$\text{Min}_{x \in X} f(x),$$

with  $x^\sharp$  an optimal solution and  $f$  not necessarily convex.

- If  $f$  is differentiable, then  $\nabla f(x^\sharp) = 0$ .
- If  $f$  is twice differentiable, then  $\nabla^2 f(x^\sharp) \succeq 0$ .
- If  $f$  is twice differentiable and  $\nabla^2 f(x_0) \succ 0$  then  $x_0$  is a local minimum.

If, in addition,  $f$  is convex then  $\nabla f(x) = 0$  is a sufficient optimality condition.



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Let  $f$  be a convex function and  $C$  a convex set. The function

$$g : x \mapsto \inf_{y \in C} f(x, y)$$

is convex.

♠ Exercise: Prove this result.

♣ Exercise: Prove that the function **distance** to a convex set  $C$  defined by

$$d_C(x) := \inf_{c \in C} \|c - x\|$$

is convex.



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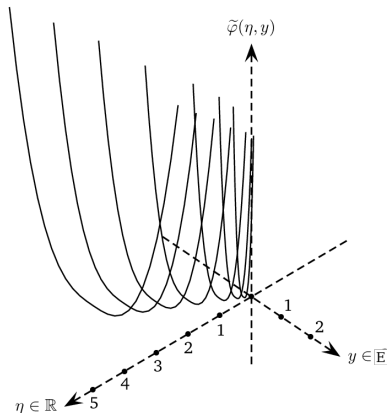
Let  $\phi : E \rightarrow \bar{\mathbb{R}}$ . The **perspective** of  $\phi$  is defined as  $\tilde{\phi} : \mathbb{R}_+^* \times E \rightarrow \mathbb{R}$  by

$$\tilde{\phi}(\eta, y) := \eta\phi(y/\eta).$$

## Theorem

$\phi$  is convex iff  $\tilde{\phi}$  is convex.

♠ Exercise: prove this result





Let  $f$  and  $g$  be proper function from  $X$  to  $\mathbb{R} \cup \{+\infty\}$ . We define

$$f \square g : x \mapsto \inf_{y \in X} f(y) + g(x - y)$$

♣ Exercise: Show that

- $f \square g = g \square f$
- If  $f$  and  $g$  are convex then so is  $f \square g$

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Let  $X$  be an Hilbert space,  $f : X \rightarrow \bar{\mathbb{R}}$  convex.

- The **subdifferential** of  $f$  at  $x \in \text{dom}(f)$  is the set of slopes of all affine minorants of  $f$  exact at  $x$ :

$$\partial f(x) := \left\{ \lambda \in X \mid f(\cdot) \geq \langle \lambda, \cdot - x \rangle + f(x) \right\}.$$

- If  $f$  is derivable at  $x$  then

$$\partial f(x) = \{ \nabla f(x) \}.$$



- If  $f : x \mapsto |x|$ , then

$$\partial f(x) = \begin{cases} -1 & \text{if } x < 0 \\ [-1, 1] & \text{if } x = 0 \\ 1 & \text{if } x > 0 \end{cases}$$

- If  $C$  is convex then, for  $x \in C$ ,  $\partial(\mathbb{I}_C)(x) = N_C(x)$   
♣ Exercise: Prove it.
- If  $f_1$  and  $f_2$  are convex and differentiable. Define  $f = \max(f_1, f_2)$ .  
Then
  - ▶ if  $f_1(x) > f_2(x)$ ,  $\partial f(x) = \{\nabla f_1(x)\}$
  - ▶ if  $f_1(x) < f_2(x)$ ,  $\partial f(x) = \{\nabla f_2(x)\}$ ;
  - ▶ if  $f_1(x) = f_2(x)$ ,  $\partial f(x) = \overline{\text{conv}}(\{\nabla f_1(x), \nabla f_2(x)\})$ .



# Subdifferential calculus



Let  $f_1$  and  $f_2$  be proper convex functions.

## Theorem

We have

$$\partial(f_1)(x) + \partial(f_2)(x) \subset \partial(f_1 + f_2)(x), \quad \forall x$$

Further if  $\text{ri}(\text{dom}(f_1)) \cap \text{ri}(\text{dom}(f_2)) \neq \emptyset$  then

$$\partial(f_1)(x) + \partial(f_2)(x) = \partial(f_1 + f_2)(x), \quad \forall x$$

When  $f_i$  is polyhedral you can replace  $\text{ri}(\text{dom}(f_i))$  by  $\text{dom}(f_i)$  in the condition.

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## Theorem

If  $f$  is convex and  $a : x \mapsto Ax + b$  with  $\text{Im}(a) \cap \text{ri}(\text{dom}(f)) \neq \emptyset$ , then

$$\partial(f \circ a)(x) = A^\top \partial f(Ax + b).$$



## Theorem

Let  $f : X \mapsto \mathbb{R} \cup \{+\infty\}$  be a convex function (not necessarily) differentiable.  $x^\#$  is a minimizer of  $f$  if and only if  $0 \in \partial f(x^\#)$ .



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## Theorem

Let  $f$  be a proper convex function and  $C$  a closed non-empty convex set such that  $\text{ri}(C) \cap \text{ri}(\text{dom}(f)) \neq \emptyset$  then  $x^\#$  is an optimal solution to

$$\min_{x \in C} f(x)$$

iff

$$0 \in \partial f(x^\#) + N_C(x^\#),$$

iff

$$\exists \lambda \in \partial f(x^\#), \quad \lambda \in -N_C(x^\#).$$

## Normal cone, Tangent cone and optimality

Let  $C$  be a convex set. We define the **tangent cone** of  $C \subset \mathbb{R}^n$  at point  $x \in C$ , as the set of directions in which you can move from  $x$  while staying in  $C$  for some time, that is

$$T_C(x) := \left\{ \lambda(y - x) \mid y \in C, \lambda \in \mathbb{R}^+ \right\}$$

In particular,  $T_C(x) = \mathbb{R}^n$  iff  $x \in \text{int}(C)$ .

♣ Exercise: Prove that  $[T_C(x)]^\oplus = -N_C(x)$ .

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Let  $f : X \times Y \rightarrow \bar{\mathbb{R}}$  be a jointly convex and proper function, and define

$$v(x) = \inf_{y \in Y} f(x, y)$$

then  $v$  is convex.

If  $v$  is proper, and  $v(x) = f(x, y^\sharp(x))$  then

$$\partial v(x) = \{g \in X \mid (g, 0) \in \partial f(x, y^\sharp(x))\}$$

proof:

$$\begin{aligned} g \in \partial v(x) &\Leftrightarrow \forall x', \quad v(x') \geq v(x) + \langle g, x' - x \rangle \\ &\Leftrightarrow \forall x', y' \quad f(x', y') \geq f(x, y^\sharp(x)) + \left\langle \begin{pmatrix} g \\ 0 \end{pmatrix}, \begin{pmatrix} x' \\ y' \end{pmatrix} - \begin{pmatrix} x \\ y^\sharp(x) \end{pmatrix} \right\rangle \\ &\Leftrightarrow \begin{pmatrix} g \\ 0 \end{pmatrix} \in \partial f(x, y^\sharp(x)) \end{aligned}$$



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- Assume  $f$  convex, then  $f$  is continuous on the relative interior of its domain, and Lipschitz on any compact contained in the relative interior of its domain.
- A proper convex function is subdifferentiable on the relative interior of its domain.
- If  $f$  is convex, it is  $L$ -Lipschitz iff  $\partial f(x) \subset B(0, L)$ ,  $\forall x \in \text{dom}(f)$

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Let  $X$  be a Hilbert space,  $f : X \rightarrow \bar{\mathbb{R}}$  be a proper function.

- The Fenchel transform of  $f$ , is  $f^* : X \rightarrow \bar{\mathbb{R}}$  with

$$f^*(\lambda) := \sup_{x \in X} \langle \lambda, x \rangle - f(x).$$

- $f^*$  is convex lsc as the supremum of affine functions.
- $f \leq g$  implies that  $f^* \geq g^*$ .
- If  $f$  is proper convex lsc, then  $f^{**} = f$ , otherwise  $f^{**} \leq f$ .

♣ Exercise: Prove the first two points



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# Fenchel transform and subdifferential



- By definition  $f^*(\lambda) \geq \langle \lambda, x \rangle - f(x)$  for all  $x$ ,
- thus we always have (Fenchel-Young)  $f(x) + f^*(\lambda) \geq \langle \lambda, x \rangle$ .
- Recall that  $\lambda \in \partial f(x)$  iff,

$$f(x') \geq f(x) + \langle \lambda, x' - x \rangle, \quad \forall x'$$

iff

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- If  $f$  proper convex lsc

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# What you have to know

- What is a **affine set**, a **convex set**, a **polyhedron**, a (convex) **cone**
- What is a **convex** function, that it is above its tangents.
- Jensen inequality
- What is a convex optimization problem. That any local minimum is a global minimum.
- The necessary optimality condition  $\nabla f(x^\#) \in [T_X(x^\#)]^\oplus$

# What you really should know

- That you can separate convex sets with a linear function
- What is the positive dual of a cone
- Basic manipulations preserving convexity (sum, cartesian product, intersection, linear projection)
- What is the domain, the sublevel of a function  $f$
- What is a lower semi-continuous function, a proper convex function
- Conditions of (strict, strong) convexity for differentiable functions
- The partial minimum of a convex function is convex
- The definition of the subdifferential.
- The definition of the Fenchel transform.
- The link between Fenchel transform and subdifferential.

# What you have to be able to do

- Show that a set is convex
- Show that a function is (strictly, strongly) convex
- Go from constrained problem to unconstrained problem using the indicator function  $\mathbb{I}_X$

# What you should be able to do

- Compute dual cones
- Use advanced results (projection, partial infimum, perspective) to show that a function or a set is convex
- Compute the Fenchel transform of simple functions